

Bayesian Methods

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Classical Statistics

Parametric Family of Densities

- A **parametric family of densities** is a set

$$\{p(y | \theta) : \theta \in \Theta\},$$

- where $p(y | \theta)$ is a density on a **sample space** \mathcal{Y} , and
- θ is a **parameter** in a [finite dimensional] **parameter space** Θ .

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- where $p(y | \theta)$ is a density on a **sample space** \mathcal{Y} , and
 - θ is a **parameter** in a [finite dimensional] **parameter space** Θ .
- This is the common starting point for a treatment of classical or Bayesian statistics.

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- (In more advanced, measure-theoretic treatments, they are each considered densities w.r.t. different base measures.)

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- Assume that $p(y | \theta)$ governs the world we are observing, for some $\theta \in \Theta$.
- If we knew the right $\theta \in \Theta$, there would be no need for statistics.
- Instead of θ , we have data \mathcal{D} : y_1, \dots, y_n sampled i.i.d. $p(y | \theta)$.
- Statistics is about how to get by with \mathcal{D} in place of θ .

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- A good point estimator will have $\hat{\theta} \approx \theta$.

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 - **Efficiency:** (Roughly speaking) $\hat{\theta}_n$ is as accurate as we can get from a sample of size n .
- **Maximum likelihood estimators** are consistent and efficient under reasonable conditions.

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- For fixed θ , $p(\mathcal{D} | \theta)$ is a density function on \mathcal{Y}^n .
- For fixed \mathcal{D} , the function $\theta \mapsto p(\mathcal{D} | \theta)$ is called the **likelihood function**:

$$L_{\mathcal{D}}(\theta) := p(\mathcal{D} | \theta).$$

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The **maximum likelihood estimator (MLE)** for θ in the model $\{p(y | \theta) : \theta \in \Theta\}$ is

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- Maximum likelihood is just one approach to getting a point estimator for θ .
- **Method of moments** is another general approach one learns about in statistics.
- Later we'll talk about **MAP** and **posterior mean** as approaches to point estimation.
 - These arise naturally in Bayesian settings.

- Parametric family of mass functions:

$$p(\text{Heads} \mid \theta) = \theta,$$

for $\theta \in \Theta = (0, 1)$.

Coin Flipping: Setup

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$$p(\text{Heads} \mid \theta) = \theta,$$

for $\theta \in \Theta = (0, 1)$.

- Note that every $\theta \in \Theta$ gives us a different probability model for a coin.

Coin Flipping: Likelihood function

- Data $\mathcal{D} = (H, H, T, T, T, T, T, H, \dots, T)$
 - n_h : number of heads
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- This is the probability of getting the flips in the order they were received.

Coin Flipping: MLE

- As usual, easier to maximize the log-likelihood function:

$$\begin{aligned}\hat{\theta}_{\text{MLE}} &= \arg \max_{\theta \in \Theta} \log L_{\mathcal{D}}(\theta) \\ &= \arg \max_{\theta \in \Theta} [n_h \log \theta + n_t \log(1 - \theta)]\end{aligned}$$

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- First order condition:

$$\begin{aligned}\frac{n_h}{\theta} - \frac{n_t}{1 - \theta} &= 0 \\ \iff \theta &= \frac{n_h}{n_h + n_t}.\end{aligned}$$

- So $\hat{\theta}_{\text{MLE}}$ is the empirical fraction of heads.

Bayesian Statistics: Introduction

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- A prior reflects our belief about θ , **before seeing any data**..

A Bayesian Model

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- ① A parametric family of densities

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- 2 A **prior distribution** $p(\theta)$ on parameter space Θ .

- Putting pieces together, we get a joint density on θ and \mathcal{D} :

$$p(\mathcal{D}, \theta) = p(\mathcal{D} | \theta)p(\theta).$$

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- Prior represents belief about θ before observing data \mathcal{D} .
- Posterior represents the **rationally “updated” belief** about θ , after seeing \mathcal{D} .

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- Where \propto means we've dropped factors independent of θ .

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- Need a prior distribution $p(\theta)$ on $\Theta = (0, 1)$.
- A distribution from the Beta family will do the trick...

Coin Flipping: Beta Prior

- **Prior:**

$$\begin{aligned}\theta &\sim \text{Beta}(\alpha, \beta) \\ p(\theta) &\propto \theta^{\alpha-1} (1-\theta)^{\beta-1}\end{aligned}$$

Figure by Horas based on the work of Krishnavedala (Own work) [Public domain], via Wikimedia Commons

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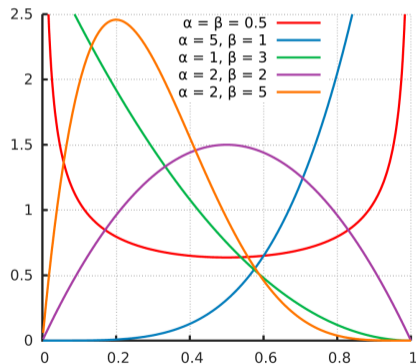


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- **Mode of Beta distribution:**

$$\arg \max_{\theta} p(\theta) = \frac{h-1}{h+t-2}$$

for $h, t > 1$.

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- Interpretation:

- Prior initializes our counts with h heads and t tails.
- Posterior increments counts by observed n_h and n_t .

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Definition

A family of distributions π is **conjugate to** parametric model P if for any prior in π , the posterior is always in π .

- The beta family is conjugate to the coin-flipping (i.e. Bernoulli) model.
- The family of all probability distributions is conjugate to any parametric model. [Trivially]

Example: Coin Flipping - Concrete Example

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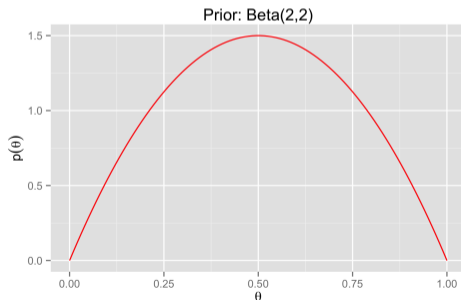
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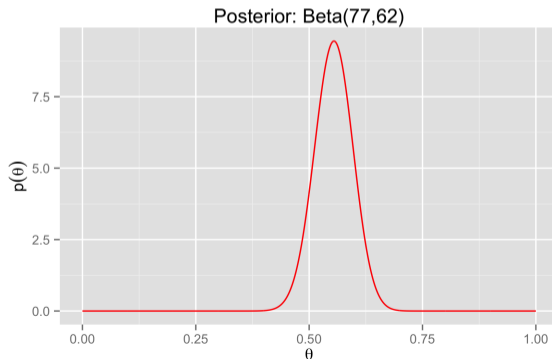
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- Heads: 75 Tails: 60

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- Heads: 75 Tails: 60
 - $\hat{\theta}_{\text{MLE}} = \frac{75}{75+60} \approx 0.556$
- **Posterior distribution:** $\theta \mid \mathcal{D} \sim \mathbf{Beta}(77, 62)$:



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- So we have posterior $\theta | \mathcal{D} \dots$
- But we want a point estimate $\hat{\theta}$ for θ .
- Common options:
 - **posterior mean** $\hat{\theta} = \mathbb{E}[\theta | \mathcal{D}]$
 - **maximum a posteriori (MAP) estimate** $\hat{\theta} = \arg \max_{\theta} p(\theta | \mathcal{D})$
 - Note: this is the **mode** of the posterior distribution

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- Extract “**credible set**” for θ (a Bayesian confidence interval).
 - e.g. Interval $[a, b]$ is a 95% **credible set** if

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- The most “Bayesian” approach is **Bayesian decision theory**:
 - Choose a loss function.
 - Find action **minimizing expected risk w.r.t. posterior**

Bayesian Decision Theory

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- Ingredients:
 - **Parameter space** Θ .
 - **Prior**: Distribution $p(\theta)$ on Θ .
 - **Action space** \mathcal{A} .
 - **Loss function**: $\ell : \mathcal{A} \times \Theta \rightarrow \mathbf{R}$.

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- A **Bayes action** a^* is an action that minimizes posterior risk:

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 - Show with approach similar to what was used in Homework #1.

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- This $\hat{\theta}$ is called the **maximum a posteriori (MAP)** estimate.
- The MAP estimate is the **mode** of the posterior distribution.

Summary

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 - For decision making, need a **loss function**.
 - Everything after that is **computation**.

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