

Gradient Boosting Practice: Poisson Response

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Suppose we're trying to predict a distribution of count from some input covariates. The simplest distribution in this situation is the Poisson distribution:

$$p(k; \lambda) = \frac{e^{-\lambda} \lambda^k}{k!}$$

on $k = 0, 1, 2, 3, \dots$ $\lambda \in (0, \infty)$.

1 Linear Conditional Probability Model

- Input: $x \in \mathbf{R}^d$.
- Output: $y \in \{0, 1, 2, \dots\}$
- Data:

$$\mathcal{D} = ((x_1, y_1), \dots, (x_n, y_n)) \in (\mathbf{R}^d \times \{0, 1, 2, \dots\})^n$$

assume is sampled i.i.d. from some distribution $P_{\mathcal{X} \times \mathcal{Y}}$.

- Action: $\lambda \in (0, \infty)$, where λ is the parameter of a Poisson distribution.

We've got to map input x to action λ in our action space, which is $(0, \infty)$.

$$x \mapsto \underbrace{w^T x}_{\text{score } s \in \mathbf{R}} \mapsto \underbrace{\lambda}_{\in (0, \infty)}$$

To map the score s into our action space, we could use the transfer function $\psi(s) = \exp(s)$. Then

$$\lambda = \exp(w^T x).$$

So if we predict λ , what's the probability of an observed count k for input vector x ?

$$\begin{aligned} p(y = k \mid x; w) &= \frac{e^{-\lambda(x)} \lambda(x)^k}{k!} \\ &= \frac{e^{-\exp(w^T x)} [\exp(w^T x)]^k}{k!}. \end{aligned}$$

The conditional likelihood for particular example (x_i, y_i) , (where y_i is a count) is

$$p(y = y_i \mid x_i; w) = \frac{e^{-\exp(w^T x_i)} [\exp(w^T x_i)]^{y_i}}{y_i!}.$$

Easier to work with the log:

$$\log p(y = y_i \mid x_i; w) = -\exp(w^T x_i) + y_i w^T x_i - \log(y_i!)$$

What do we need to find to fit this model? w . our strategy is to use maximum log-likelihood:

$$\begin{aligned} \log L_{\mathcal{D}}(w) &= \log p(\mathcal{D}; w) \\ &= \sum_{i=1}^n \log p(y = y_i \mid x_i; w) \\ &= \sum_{i=1}^n [-\exp(w^T x_i) + y_i w^T x_i - \log(y_i!)] \end{aligned}$$

So find w maximizing this log-likelihood and we're done. Can use standard gradient based methods.

2 Nonlinear approach

In a nonlinear approach, we'll replace the linear score function $s = w^T x$ with a nonlinear function $s = f(x)$:

$$x \mapsto \underbrace{f(x)}_{\text{score } s \in \mathbf{R}} \mapsto \underbrace{\lambda}_{\in (0, \infty)}.$$

Again, we can use the transfer function $\psi(s) = \exp(s)$. So

$$\lambda = \exp(f(x)).$$

For score function f , the probability of $y_i | x_i$ is:

$$p(y = y_i | x_i; f) = \frac{e^{-\exp(f(x_i))} [\exp(f(x_i))]^{y_i}}{y_i!}.$$

Easier to work with the log:

$$\log p(y = y_i | x_i; f) = -\exp(f(x_i)) + y_i f(x_i) - \log(y_i!)$$

Somehow we want to find a function f that gives high log-likelihood to our observed data:

$$\log L_{\mathcal{D}}(w) = \sum_{i=1}^n [-\exp(f(x_i)) + y_i f(x_i) - \log(y_i!)]$$

3 Gradient Boosting Approach

Let's differentiate $\log p(y = y_i | x_i; f)$ w.r.t. $f(x_i)$:

$$\frac{\partial}{\partial f(x_i)} \log p(y = y_i | x_i; f) = -\exp(f(x_i)) + y_i$$

Now differentiating the full log-likelihood is

$$\begin{aligned} \frac{\partial}{\partial f(x_i)} [\log L_{\mathcal{D}}(f)] &= \frac{\partial}{\partial f(x_i)} [-\exp(f(x_i)) + y_i f(x_i) - \log(y_i!)] \\ &= -\exp(f(x_i)) + y_i \end{aligned}$$

So optimal unconstrained step direction for changing the vector of evaluations $\mathbf{f} = (f(x_1), \dots, f(x_n))$ is

$$-\mathbf{g} = (-y_1 + \exp(f(x_1)), \dots, -y_n + \exp(f(x_n)))$$

Fix some base hypothesis space \mathcal{H} of functions $h : \mathbf{R}^d \rightarrow \mathbf{R}$. Then, our actual step direction will be the $h \in \mathcal{H}$ that best fits $-\mathbf{g}$ in the least squares sense:

$$\begin{aligned} &\arg \min_{h \in \mathcal{H}} \sum_{i=1}^n (-\mathbf{g}_i - h(x_i))^2 \\ &= \arg \min_{h \in \mathcal{H}} \sum_{i=1}^n ([-y_i + \exp(f(x_i))] - h(x_i))^2 \end{aligned}$$

So to recap:

1. Up to this point, our score function is f .
2. We want to improve f .
3. The optimal step direction for $f(x_i)$ is $-y_i + \exp(f(x_i))$. We can evaluate this. It's a real number.
4. So we have a bunch of $(x_i, -\mathbf{g}_i)$ pairs that we will use regression over \mathcal{H} to fit.

Then we add something like $0.1h$ to f and repeat.