Features

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Learning Objectives

- Understand where a feature map sits in a machine learning pipeline.
- Understand that featurization/featuring mapping is inherently required to allow predictors to ingest many types of data.
- Understand how feature extraction can be used to extend the power of linear methods.
- Build pipelines with expanded feature spaces using the sklearn ecosystem.
Feature Extraction
The Input Space $\mathcal{X}$

- Our general learning theory setup: no assumptions about $\mathcal{X}$
- But $\mathcal{X} = \mathbb{R}^d$ for the specific methods we’ve developed:
  - Ridge regression
  - Lasso regression
  - Linear SVM
Definition

Mapping an input from $\mathcal{X}$ to a vector in $\mathbb{R}^d$ is called feature extraction or featurization.
Two motivations for thinking about feature extraction:
- Motivation 1 – consuming inputs that are not natively in $\mathbb{R}^d$ – examples?
  - Text documents
  - Image files
  - Sound recordings
  - DNA sequences
- But everything in a computer is a sequence of numbers?
  - The $i$th entry of each sequence should have the same “meaning”
  - All the sequences should have the same length
The machine learning pipeline

Raw data → Features → Models → Deploy in production → Predictions

I fell in love the instant I laid my eyes on that puppy. His big eyes and playful tail, his soft furry paws, ...

Feature Templates
Example: Detecting Email Addresses

- Task: Predict whether a string is an email address
- Could use domain knowledge and write down:

  
  ![Image of feature extractor](image)

  
  - length > 10 : 1
  - fracOfAlpha : 0.85
  - contains_@ : 1
  - endsWith_com : 1
  - endsWith_org : 0

- But this was ad-hoc, and maybe we missed something.
- Could be more systematic?

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Feature Templates

Definition (informal)

A feature template is a group of features all computed in a similar way.

- Input: abc@gmail.com

Feature Templates

- Length greater than ____
- Last three characters equal ____
- Contains character ____
Feature Template: Last Three Characters Equal __

- Don’t think about which 3-letter suffixes are meaningful...
- Just include them all.

```
endsWith_aaa : 0
endsWith_aab : 0
endsWith_aac : 0
...
endsWith_com : 1
...
endsWith_zzz : 0
```

- With regularization, our methods will not be overwhelmed.

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Feature Vector Representations

Array representation (good for dense features):

\[ [0.85, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0] \]

Map representation (good for sparse features):

\{"fracOfAlpha": 0.85, "contains_@": 1\}

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Feature Vector Representations

- **Arrays**
  - assumed fixed ordering of the features
  - appropriate when significant number of nonzero elements
    (“dense feature vectors”)
  - very efficient in space and speed (and you can take advantage of GPUs)

- **Map (a “dict” in Python)**
  - best for *sparse feature vectors* (i.e. few nonzero features)
  - features not in the map have default value of zero
  - Python code for “ends with last 3 characters”:
    
    ```python
    {"endsWith_"+x[-3:]: 1}.
    ```
  - On "example string" we’d get {"endsWith_ing": 1}.
  - Has overhead compared to arrays, so much slower for dense features.

Question: if we have a sparse feature vector, what are the implications for preprocessing?

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Feature Map – ingesting inputs not natively in $\mathbb{R}^d$
Example: Classifying documents from 20 newsgroups

- Context: The newsgroups dataset comprises around 18000 newsgroups posts on 20 topics.
- We'll restrict ourselves to classifying posts within 4 topics:
  - 'alt.atheism'
  - 'soc.religion.christian'
  - 'comp.graphics'
  - 'sci.med'.
- Thanks to the sklearn team for this worked example (at http://scikit-learn.org/stable/tutorial/text_analytics/working_with_text_data.html).

See https://github.com/davidrosenberg/mlcourse/blob/gh-pages/Notebooks/Features/test_BOW.ipynb for this example in full.
Example: Classifying documents from 20 newsgroups

Example Document:

From: sd345@city.ac.uk (Michael Collier)
Subject: Converting images to HP LaserJet III?
Nntp-Posting-Host: hampton
Organization: The City University
Lines: 14

Does anyone know of a good way (standard PC application/PD utility) to convert tif/img/tga files into LaserJet III format. We would also like to do the same, converting to HPGL (HP plotter) files.

Please email any response.

Is this the correct group?

Thanks in advance. Michael.

--

Michael Collier (Programmer)                              The Computer Unit,
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Tel: 071 477-8000 x3769                                  London,
Fax: 071 477-8565                                          EC1V 0HB.
Example: Classifying documents from 20 newsgroups

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Does anyone know of a good way (standard PC application/PD utility) to convert tif/img/tga files into LaserJet III format. We would also like to do the same, converting to HPGL (HP plotter) files.

Please email any response.

- What feature maps could we apply over these sorts of documents?
- A simple approach – bag-of-words (BOW).
  - Assign a fixed integer id to each word occurring in any document of the training set.
  - For each document $i$, count the number of occurrences of each word $w$ and store it (sparsely) as $doc_i[w] = j_w == \text{count of word } w \text{ in document } i$.
  - The BOW representation implies that $n_{\text{features}}$ is the number of distinct words in the corpus.
  - What is the feature map $\phi(x)$?
  - $\phi(x) = [j_{\text{word}_1}, \cdots, j_{\text{word}_{n_{\text{words}}}}]$
Example: Classifying documents from 20 newsgroups

- Here’s the classifier we’ll fit (note we’re adding the TfidfTransformer to scale by inverse document frequency, since it improves performance on this task – if you’re not familiar with TF-IDF see the docs).

```python
from sklearn.linear_model import SGDClassifier
from sklearn.feature_extraction.text import CountVectorizer, TfidfTransformer
from sklearn.pipeline import Pipeline
text_clf = Pipeline([('vect', CountVectorizer()),
                     ('tfidf', TfidfTransformer()),
                     ('clf', SGDClassifier(loss='hinge', penalty='l2',
                                            alpha=1e-3, random_state=42,
                                            max_iter=5, tol=None))],
                     name='text_clf')
text_clf.fit(twenty_train.data, twenty_train.target)
```

- Which named steps in this Pipeline comprise our feature map $\phi$?
Example: Classifying documents from 20 newsgroups

```python
predicted = text_clf.predict(docs_test)
np.mean(predicted == twenty_test.target)
```

0.9127829560585885

```python
from sklearn import metrics
print(metrics.classification_report(twenty_test.target, predicted, target_names=twenty_test.target_names))
```

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>alt.atheism</td>
<td>0.95</td>
<td>0.81</td>
<td>0.87</td>
<td>319</td>
</tr>
<tr>
<td>comp.graphics</td>
<td>0.88</td>
<td>0.97</td>
<td>0.92</td>
<td>389</td>
</tr>
<tr>
<td>sci.med</td>
<td>0.94</td>
<td>0.90</td>
<td>0.92</td>
<td>396</td>
</tr>
<tr>
<td>soc.religion.christian</td>
<td>0.90</td>
<td>0.95</td>
<td>0.93</td>
<td>398</td>
</tr>
<tr>
<td>avg / total</td>
<td>0.92</td>
<td>0.91</td>
<td>0.91</td>
<td>1502</td>
</tr>
</tbody>
</table>

Key takeaway: need feature map $\phi$ when dealing with inputs not natively in $\mathbb{R}^d$. 
Motivation

- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Think about HW2.

What was our feature map $\phi(x)$? $\phi(x) \in \mathbb{R}^k$ for what $k$?

$\phi(x) = [1(x \geq \frac{1}{400}), \ldots, 1(x \geq \frac{399}{400})]$
Motivation

- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Think about HW2.

- Why did we use this feature map instead of just learning a prediction function $y \sim x$?
Motivation

- Two motivations for thinking about feature extraction:
  - Motive 2 – Improving performance. Toy Example:

  **Boston House Prices dataset**
  ================================

Notes
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Data Set Characteristics:

: **Number of Instances**: 506

: **Number of Attributes**: 13 numeric/categorical predictive

: **Median Value (attribute 14)** is usually the target
Two motivations for thinking about feature extraction:

- Motive 2 – Improving performance. Toy Example:

```python
from sklearn.linear_model import ElasticNetCV
en = ElasticNetCV(cv = 5)

en.fit(np.log(train_X[['LSTAT']]), train_y)
en.score(np.log(test_X[['LSTAT']]), test_y)
0.74651286928253746

en.fit(train_X[['LSTAT']], train_y)
en.score(test_X[['LSTAT']], test_y)
0.5789447566257272
```

See https://github.com/davidrosenberg/mlcourse/blob/gh-pages/Notebooks/Features/simple_feature_transformations.ipynb
Motivation

- We’ll be looking at regression examples throughout this lab.
- Using Elastic Net in sklearn, the default score method returns the coefficient of determination $R^2$ of the prediction.
- Recall:

  - The total sum of squares (proportional to the variance of the data):
    \[ SS_{\text{tot}} = \sum_i (y_i - \bar{y})^2, \]
  
  - The regression sum of squares, also called the explained sum of squares:
    \[ SS_{\text{reg}} = \sum_i (f_i - \bar{y})^2, \]
  
  - The sum of squares of residuals, also called the residual sum of squares:
    \[ SS_{\text{res}} = \sum_i (y_i - f_i)^2 = \sum_i e_i^2 \]

  The most general definition of the coefficient of determination is

  \[ R^2 \equiv 1 - \frac{SS_{\text{res}}}{SS_{\text{tot}}}. \]
Motivation

- Key idea: instead of using more flexible (i.e. non-linear) models, build better features.
Handling Nonlinearity with Linear Methods
Example Task: Predicting Health

- General Philosophy: Extract every feature that might be relevant
- Features for medical diagnosis
  - height
  - weight
  - body temperature
  - blood pressure
  - etc...

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
For linear predictors, it’s important **how** features are added

Three types of nonlinearities can cause problems:

1. Non-monotonicity
2. Saturation
3. Interactions between features
Non-monotonicity: The Issue

- Feature Map: $\phi(x) = [1, \text{temperature}(x)]$
- Action: Predict health score $y \in \mathbb{R}$ (positive is good)
- Hypothesis Space $\mathcal{F} = \{\text{affine functions of temperature}\}$
- Issue:
  - Health is not an affine function of temperature.
  - Affine function can either say
    - Very high is bad and very low is good, or
  - Very low is bad and very high is good,
  - But here, both extremes are bad.

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Non-monotonicity: Solution 1

- Transform the input:

\[ \phi(x) = \left[ 1, \{\text{temperature}(x) - 37 \}^2 \right], \]

where 37 is “normal” temperature in Celsius.

- Ok, but this requires domain knowledge
  - Do we really need that?

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Non-monotonicity: Solution 2

- Think less, put in more:

  \[ \phi(x) = [1, \text{temperature}(x), \{\text{temperature}(x)\}^2] . \]

- More expressive than Solution 1.

General Rule

Features should be simple building blocks that can be pieced together.
Saturation: The Issue

- Setting: Find products relevant to user’s query
- Input: Product $x$
- Action: Score the relevance of $x$ to user’s query
- Feature Map:
  \[ \phi(x) = [1, N(x)], \]

  where $N(x) =$ number of people who bought $x$.
- We expect a monotonic relationship between $N(x)$ and relevance, but...

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Saturation: The Issue

Is relevance linear in $N(x)$?

- Relevance score reflects confidence in relevance prediction.
- Are we 10 times more confident if $N(x) = 1000$ vs $N(x) = 100$?

- Bigger is better... but not that much better.

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Saturation: Solve with nonlinear transform

- Smooth nonlinear transformation:

\[ \phi(x) = [1, \log\{1 + N(x)\}] \]

- \( \log(\cdot) \) good for values with large dynamic ranges

- *Does it matter what base we use in the log?*
Saturation: Solve by discretization

- Discretization (a discontinuous transformation):
  \[ \phi(x) = (1(5 \leq N(x) < 10), 1(10 \leq N(x) < 100), 1(100 \leq N(x))) \]

- Sometimes we might prefer one-sided buckets
  \[ \phi(x) = (1(5 \leq N(x)), 1(10 \leq N(x)), 1(100 \leq N(x))) \]

- Why? Hint: What’s the effect of regularization on the parameters for rare buckets?
- Small buckets allow quite flexible relationship
Interactions: The Issue

- Input: Patient information $x$
- Action: Health score $y \in \mathbb{R}$ (higher is better)
- Feature Map
  
  $$\phi(x) = [\text{height}(x), \text{weight}(x)]$$

- Issue: It’s the weight **relative** to the height that’s important.
- Impossible to get with these features and a linear classifier.
- Need some **interaction** between height and weight.

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From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Interactions: Approach 1

- Google “ideal weight from height”
- J. D. Robinson’s “ideal weight” formula (for a male):
  \[
  \text{weight}(\text{kg}) = 52 + 1.9[\text{height}(\text{in}) - 60]
  \]
- Make score square deviation between height(h) and ideal weight(w)
  \[
  f(x) = (52 + 1.9[h(x) - 60] - w(x))^2
  \]
- WolframAlpha for complicated Mathematics:
  \[
  f(x) = 3.61h(x)^2 - 3.8h(x)w(x) - 235.6h(x) + w(x)^2 + 124w(x) + 3844
  \]

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Interactions: Approach 2

- Just include all second order features:

\[ \phi(x) = \begin{bmatrix} 1, h(x), w(x), h(x)^2, w(x)^2, \underbrace{h(x)w(x)}_{\text{cross term}} \end{bmatrix} \]

- More flexible, no Google, no WolframAlpha.

General Principle

Simpler building blocks replace a single “smart” feature.

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From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Definition

A **predicate** on the input space $\mathcal{X}$ is a function $P : \mathcal{X} \rightarrow \{\text{True, False}\}$.

- Many features take this form:
  - $x \mapsto s(x) = 1$ (subject is sleeping)
  - $x \mapsto d(x) = 1$ (subject is driving)
- For predicates, interaction terms correspond to **AND** conjunctions:
  - $x \mapsto s(x)d(x) = 1$ (subject is sleeping AND subject is driving)
So What’s Linear?

- Non-linear feature map $\phi : \mathcal{X} \to \mathbb{R}^d$
- Hypothesis space:
  \[ \mathcal{F} = \{ f(x) = w^T \phi(x) \mid w \in \mathbb{R}^d \} . \]
- Linear in $w$? Yes.
- Linear in $\phi(x)$? Yes.
- Linear in $x$? No.
  - Linearity not even defined unless $\mathcal{X}$ is a vector space

Key Idea: Non-Linearity

- Nonlinear $f(x)$ is important for expressivity.
- $f(x)$ linear in $w$ and $\phi(x)$: makes finding $f^*(x)$ much easier

From Percy Liang’s "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Geometric Example: Two class problem, nonlinear boundary

- With linear feature map $\phi(x) = (x_1, x_2)$ and linear models, no hope
- With appropriate nonlinearity $\phi(x) = (x_1, x_2, x_1^2 + x_2^2)$, piece of cake.

Video: [http://youtu.be/3liCbRZPrZA](http://youtu.be/3liCbRZPrZA)

From Percy Liang's "Lecture 3" slides from Stanford’s CS221, Autumn 2014.
Expressivity of Hypothesis Space

Consider a linear hypothesis space with a feature map $\phi : \mathcal{X} \rightarrow \mathbb{R}^d$:

$$\mathcal{F} = \{ f(x) = w^T \phi(x) \}$$

We can grow the linear hypothesis space $\mathcal{F}$ by adding more features.

From Percy Liang's "Lecture 3" slides from Stanford's CS221, Autumn 2014.
Example 1: Boston housing and Abalone
Boston Housing

- Let’s revisit the Boston housing dataset from the start of lab.
- We’re going to be predicting the median house values in Boston suburbs.
- We’ll build our feature map using sklearn and sklearn_pandas

```python
import pandas as pd
import numpy as np

from sklearn.base import TransformerMixin
from sklearn.preprocessing import OneHotEncoder, LabelEncoder
from sklearn_pandas import DataFrameMapper
from sklearn.pipeline import Pipeline
from sklearn.linear_model import ElasticNetCV
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import PolynomialFeatures

import seaborn as sns
import matplotlib.pyplot as plt
%matplotlib inline
```
Boston Housing

- Set up data:

```python
from sklearn.datasets import load_boston

data = load_boston()
df = data.data
cols = ['CRIM', 'ZN', 'INDUS', 'CHAS', 'NOX',
        'RM', 'AGE', 'DIS', 'RAD', 'TAX',
        'PTRATIO', 'B', 'LSTAT']
df = pd.DataFrame(df, columns=cols)
train_X, test_X, train_y, test_y = train_test_split(df, data.target,
                                                    test_size=0.2,
                                                    random_state = 2142018)

categorical = ['CHAS', 'RAD']
numeric = ['CRIM', 'ZN', 'INDUS', 'NOX', 'RM',
          'AGE', 'DIS', 'TAX', 'PTRATIO', 'B',
          'LSTAT']

See https://github.com/davidrosenberg/mlcourse/blob/gh-pages/Notebooks/Features/polynomial_feature_comparison.ipynb
```

David S. Rosenberg and Ben Jakubowski (NYU)
Feature map 1– looking at the code, what is the feature map $\phi_1$?

```python
mapper = DataFrameMapper(  
    [(col, None) for col in numeric] +  
    [(col, OneHotStrings()) for col in categorical]
)

pipe = Pipeline([  
    ('mapper', mapper),  
    ('clf', ElasticNetCV(cv=10,  
        l1_ratio=[.5, .7, .9, .95, .99, 1],  
        normalize=True))
])

pipe.fit(train_X, train_y)

print('Train score: ', pipe.score(train_X, train_y))
print('Test score: ', pipe.score(test_X, test_y))
```

$\phi_1(X)$ dummy encodes categoricals and passes numeric features untouched.
Feature map 2—looking at the code, what is the feature map $\phi_2$?

```python
mapper2 = DataFrameMapper([[(numeric, PolynomialFeatures(degree=2))] + 
[(col, OneHotStrings()) for col in categorical]]

pipe2 = Pipeline([('mapper',mapper2), ('clf', ElasticNetCV(cv=10, l1_ratio=[.1, .5, .7, .9, .95, .99, 1], normalize=True))])

pipe2.fit(train_X, train_y)

print('Train score:',pipe2.score(train_X, train_y))
print('Test score:',pipe2.score(test_X, test_y))
```

- $\phi_2(X)$ dummy encodes categoricals and maps numeric features to polynomial features of degree $d \leq 2$. 
Abalone

- Here we are using the abalone dataset – predicting the number of rings on an abalone (a kind of shellfish).
- Set up data:

```python
df = pd.read_csv('http://archive.ics.uci.edu/ml/machine-learning-databases/' +
                 'abalone/abalone.data',
                 header=None)

df = df.rename(columns={
    0:'sex', 1:'length', 2:'diameter', 3:'height',
    4:'whole_weight', 5:'shucked_weight', 6:'viscera_weight',
    7:'shell_weight', 8:'rings'
})
categorical = ['sex']
numeric = ['length', 'diameter', 'height',
           'whole_weight', 'shucked_weight',
           'shell_weight']

train_X, test_X, train_y, test_y = train_test_split(df.drop('rings', axis=1),
                                                     df['rings'],
                                                     random_state=42)
```

See https://github.com/davidrosenberg/mlcourse/blob/gh-pages/Notebooks/Features/polynomial_feature_comparison.ipynb
\( \phi_1(X) \) dummy encodes categoricals and passes numeric features untouched.

```python
mapper = DataFrameMapper(
    [(col, None) for col in numeric] + \
    [(col, OneHotStrings()) for col in categorical])

pipe = Pipeline([
    ('mapper', mapper),
    ('clf', ElasticNetCV(cv=10,
        l1_ratio=[.1, .5, .7, .9, .95, .99, 1],
        normalize=True))
])

pipe.fit(train_X, train_y)

print('Train score: ', pipe.score(train_X, train_y))
print('Test score: ', pipe.score(test_X, test_y))

Train score:  0.528393673016
Test score:  0.534127249172
\( \phi_2(X) \) dummy encodes categoricals and maps numeric features to polynomial features of degree \( d \leq 2 \).

```python
define your code here...```

```
Train score: 0.559442492704
Test score: 0.554318625419
```
Comparing performance

- Why did the performance improve much more for the Boston Housing dataset versus the Abalone dataset when we used map 2?

- What is the Bayes prediction function for square loss?
- If $E[Y|X]$ is linear in $\phi_1(X)$, will we improve performance using $\phi_2(X)$?
- Do we typically know in advance the structure of $E[Y|X]$?
Example 2: Two moons data
Two moons setup

From Alice Zheng and Amanda Casari’s *Feature Engineering for Machine Learning*. What feature maps might be helpful for this problem? We’ll try binning data instances using k-means – let’s look at the transformers (*in notebook*).

See https://github.com/davidrosenberg/mlcourse/blob/gh-pages/Notebooks/Features/vector_quantization.ipynb
Two moons setup

- Here’s the pipeline. First, notice the sklearn class FeatureUnion, which let’s us easily apply multiple feature maps over an input array.
- What is the feature map $\phi(X)$? What will `transformed.shape[1]` equal?

```python
pipe = Pipeline([
    ('feats', FeatureUnion([
        ('kmeans', KMeansFeaturizer(k=100, random_state=2052018)),
        ('ID', IdentityFeaturizer())
    ])),
    ('clf', LogisticRegressionCV())
])

pipe.fit(training_data, training_labels)

# Just to make sure it's clear what this does:
transformed = pipe.named_steps['feats'].transform(training_data)

transformed.shape
```

- $\phi(X) = [X_1, X_2, \mathbb{1}[(X_1, X_2) \text{ binned to centroid } 1], \cdots, \mathbb{1}[(X_1, X_2) \text{ binned to centroid } 100]]$
Two moons setup

- Here’s the pipeline. First, notice the sklearn class FeatureUnion, which let’s us easily apply multiple feature maps over an input array.
- What is the feature map $\phi(X)$? What will `transformed.shape[1]` equal?

```python
pipe = Pipeline([  
    ('feats', FeatureUnion([  
        ('kmeans', KMeansFeaturizer(k=100, random_state=2052018)),  
        ('ID', IdentityFeaturizer())  
    ])),  
    ('clf', LogisticRegressionCV())  
])

pipe.fit(training_data, training_labels)

# Just to make sure it's clear what this does:
transformed = pipe.named_steps['feats'].transform(training_data)

transformed.shape

(2000, 102)
```
Let’s fit this pipe, and compare to a baseline logistic regression over just $\phi_I(X) = X$.

We see performance improve.
Two moons feature map

- Here’s the voronoi diagram after fitting the KMeansFeaturizer (fit in pipe.fit call).

- Intuitively, why did this improve performance?
Think back to the 1D discretization discussed earlier – which map is this analogous to?

\[ \phi_2(x) = (1(5 \leq N(x) < 10), 1(10 \leq N(x) < 100), 1(100 \leq N(x))) \]

\[ \phi_1(x) = (1(5 \leq N(x)), 1(10 \leq N(x)), 1(100 \leq N(x))) \]
Here’s a comparison of decision boundaries (note made using mlexend).

What’s with the plotted decision boundaries? I thought logistic regression was linear?
What’s with the plotted decision boundaries? I thought logistic regression was linear?

Both decision boundaries are affine, but with k-means embedding it’s affine in $\mathbb{R}^{102}$. 
Learning Objectives

- Understand where a feature map sits in a machine learning pipeline.
- Understand that featurization/featuring mapping is inherently required to allow predictors to ingest many types of data.
- Understand how feature extraction can be used to extend the power of linear methods.
- Build pipelines with expanded feature spaces using the sklearn ecosystem.